

AI in Speech Recognition and Voice Control

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Overview

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- 4 Robust ASR
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Introduction

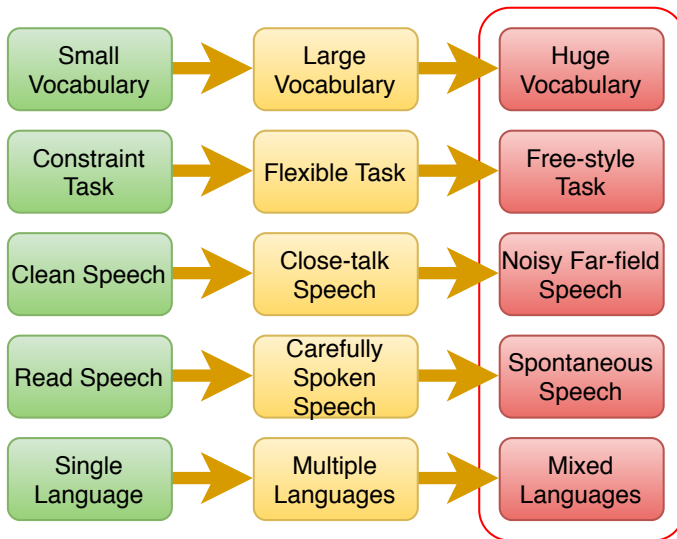
- Upswing of **automatic speech recognition (ASR)** over the last decade: *deep learning has revolutionized ASR!*
 - 1 Availability of a huge amount of speech data
 - 2 Powerful computational resources (**GPUs**)



[1] IWSDS, <http://www.iwsds.org/>

- Tons of applications:
 - 1 Search-by-voice, voice assistants, gaming, dictation, in-vehicle systems...
 - 2 Low-resource **keyword spotting (KWS)** for hearing assistive devices ([2] I. López-Espejo et al., "Improved External Speaker-Robust Keyword Spotting for Hearing Assistive Devices". IEEE/ACM Transactions on Audio, Speech, and Language Processing, 2020)

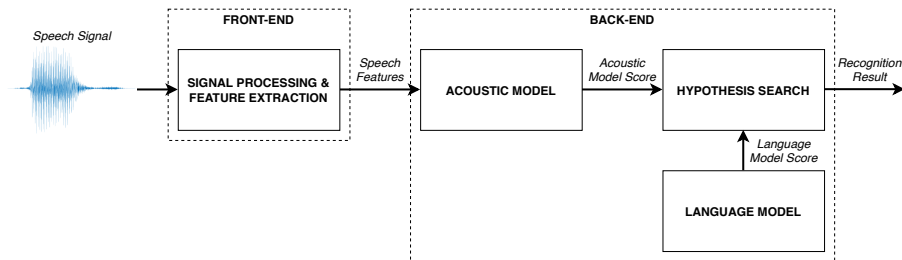
Introduction



[3] D. Yu and L. Deng, "Automatic Speech Recognition: A Deep Learning Approach". Springer, 2015

ASR Overview

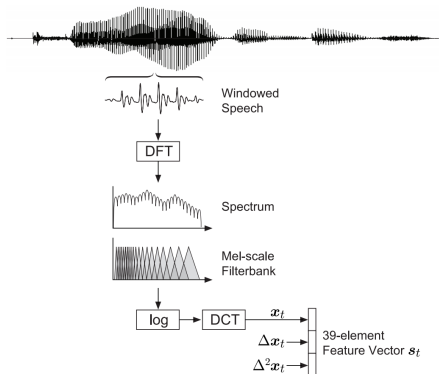
- Architecture overview of an ASR system:



- Basic ASR components:

- 1 **Signal processing & feature extraction:** log-Mel spectra, Mel-frequency cepstral coefficients (**MFCCs**)...
- 2 **Acoustic model (AM):** it integrates knowledge about acoustics and phonetics
- 3 **Language model (LM):** it estimates the probability of a hypothesized word sequence (LM score) by learning the correlation among words from text corpora
- 4 **Hypothesis search:** it outputs the word sequence with the highest score as the recognition result

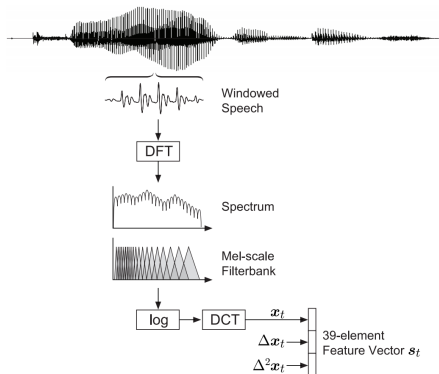
ASR Overview: Front-end



[4] H. Liao, "Uncertainty Decoding for Noise Robust Speech Recognition". Ph.D. thesis (University of Cambridge), 2007

- Desirable properties of speech features: **discriminative**, **compact** and **robust** to acoustic distortions (e.g., ambient/background noise)
- Depending on acoustic modeling...
 - 1 Gaussian mixture models (**GMMs**): use of coefficient derivatives
 - 2 Deep neural networks (**DNNs**): use of temporal context

ASR Overview: Front-end

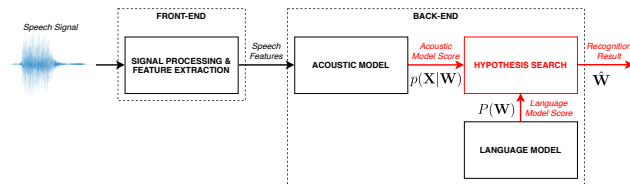


[4] H. Liao, "Uncertainty Decoding for Noise Robust Speech Recognition". Ph.D. thesis (University of Cambridge), 2007

- MFCCs better fit GMM-based acoustic models (diagonal covariance matrices, less complexity)
- Log-Mel spectra better fit DNN-based acoustic models (exploitation of spectro-temporal correlations)

ASR Overview: Back-end

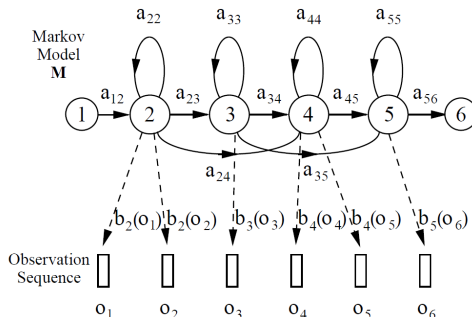
- The goal in ASR is to find the most likely sequence of words $\mathbf{W} = (w_1, w_2, \dots, w_m)$ from a set of feature vectors $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_T)$
- **Maximum a posteriori (MAP) estimation problem:**
 $\hat{\mathbf{W}} = \arg \max_{\mathbf{W}} P(\mathbf{W}|\mathbf{X}) = \arg \max_{\mathbf{W}} p(\mathbf{X}|\mathbf{W})P(\mathbf{W})$
- The **Viterbi algorithm** allows us the decoding of \mathbf{W} from the observations \mathbf{X}



- To find out $p(\mathbf{X}|\mathbf{W})$, we require both the **lexicon** (i.e., the mapping between the written words that can be recognized and the word phonetic transcriptions) and the **acoustic model**

ASR Overview: Back-end

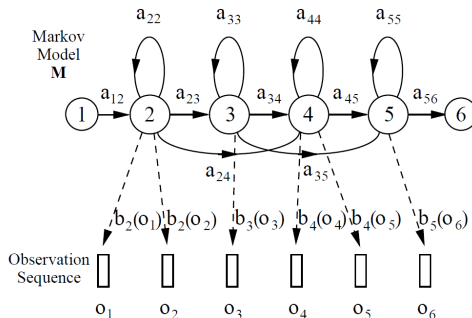
- The **acoustic model** is responsible for providing $p(\mathbf{X}|\mathbf{W})$
- Every word $w_i \in \mathbf{W}$, $i = 1, \dots, m$, is normally decomposed into simpler acoustic units (i.e., monophones or triphones) from the lexicon
- Each of these acoustic units is modeled by a **hidden Markov model (HMM)** with continuous density functions (*variable speed of speech*)
- **Remember:** HMM parameters are obtained by maximum likelihood estimation using the **Baum-Welch (EM)** algorithm



[5] S. Young *et al.*, "The HTK Book (for HTK Version 3.4)". Cambridge University Engineering Department, 2006

ASR Overview: Back-end

- Each distribution $b_j(\mathbf{o} = \mathbf{x}_t)$ expresses the probability that the feature vector \mathbf{x}_t is observed at state s_j
- Modeling of the output observation distributions of the HMM states
 - Using GMMs: $b_j(\mathbf{x}_t|s_j) = \sum_{k=1}^{\mathcal{K}} P(k|s_j)\mathcal{N}(\mathbf{x}_t | \boldsymbol{\mu}_{s_j}^{(k)}, \boldsymbol{\Sigma}_{s_j}^{(k)})$
 - It is much better to use **DNNs** to produce the state emission likelihoods!*



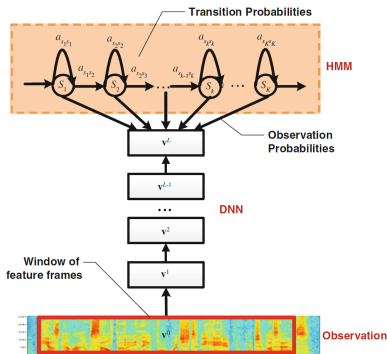
[5] S. Young *et al.*, "The HTK Book (for HTK Version 3.4)". Cambridge University Engineering Department, 2006

ASR Overview: Back-end

- $p(\mathbf{X}|\mathbf{W})$ can be calculated by summing over all the possible state sequences $\mathbf{q} = (q_1, \dots, q_T)$ that can produce \mathbf{W} :
$$p(\mathbf{X}|\mathbf{W}) = \sum_{\mathbf{q}} \prod_{t=1}^T p(\mathbf{x}_t|q_t)P(q_t|q_{t-1})$$
- $P(\mathbf{W})$ depends on the linguistic task. Under the N -gram approach (usually, $N = 2$ or $N = 3$): $P(\mathbf{W}) = \prod_{i=1}^m P(w_i|w_{i-1}, \dots, w_{i-N+1})$
- From N -gram to connectionist approaches: recurrent neural networks (RNNs) are widely used to fit a probabilistic model to compute $P(\mathbf{W})$
- Macromodel λ integrates the acoustic and language models
- The optimal state sequence $\hat{\mathbf{q}}$ from which \mathbf{W} is recovered is estimated by the Viterbi algorithm:
$$\hat{\mathbf{q}} = \arg \max_{\mathbf{q}} p(\mathbf{q}, \mathbf{X}|\lambda)$$

DNN-HMM Hybrid ASR

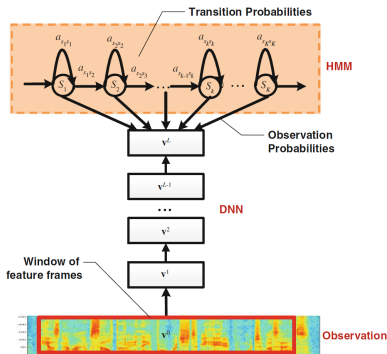
- Context-dependent (CD) DNN-HMM systems significantly outperform classical GMM-HMM systems on many large-vocabulary continuous speech recognition (**LVCSR**) tasks:
 - The output units of the DNN are senones (i.e., tied triphone states) instead of monophone states



[3] D. Yu and L. Deng, "Automatic Speech Recognition: A Deep Learning Approach". Springer, 2015

DNN-HMM Hybrid ASR

- *Important!* We do **not** use one DNN per state: a single DNN is trained to estimate the conditional state posterior probability $p(q_t = s_j | \mathbf{x}_t)$ for all states $\{s_j; j = 1, \dots, S\}$

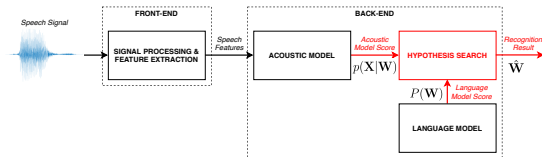


[3] D. Yu and L. Deng, "Automatic Speech Recognition: A Deep Learning Approach". Springer, 2015

DNN-HMM Hybrid ASR

- **Decoding in DNN-HMM ASR systems:**

- As for GMM-HMM ASR, $\hat{\mathbf{W}} = \arg \max_{\mathbf{W}} p(\mathbf{X}|\mathbf{W})P(\mathbf{W})$, where the AM score is $p(\mathbf{X}|\mathbf{W}) = \sum_{\mathbf{q}} \prod_{t=1}^T p(\mathbf{x}_t|q_t)P(q_t|q_{t-1})$
- In DNN-HMM ASR,
$$p(\mathbf{x}_t|q_t = s_j) = \frac{p(q_t = s_j|\mathbf{x}_t)P(\mathbf{x}_t)}{P(s_j)} \Rightarrow \bar{p}(\mathbf{x}_t|q_t = s_j) = \frac{p(q_t = s_j|\mathbf{x}_t)}{P(s_j)}$$
- The prior probability of each senone, $P(s_j) = T_{s_j}/T$, is estimated from the training set
- $p(q_t = s_j|\mathbf{x}_t)$ is given by the DNN!



- **Training DNN-HMM ASR systems (I):**

- Embedded Viterbi algorithm (\mathbb{S} is the training set):

- ① $hmm0 \leftarrow \text{TrainCD-GMM-HMM}(\mathbb{S});$
- ② $stateAlignment \leftarrow \text{ForcedAlignmentWithGMMHMM}(\mathbb{S}, hmm0);$
- ③ $stateToSenoneIDMap \leftarrow \text{GenerateStateToSenoneIDMap}(hmm0);$
- ④ $featureSenoneIDPairs \leftarrow$
 $\text{GenerateDNNTrainingSet}(stateToSenoneIDMap, stateAlignment);$
- ⑤ $ptdnn \leftarrow \text{PretrainDNN}(\mathbb{S});$
- ⑥ $hmm \leftarrow \text{ConvertGMMHMMToDNNHMM}(hmm0, stateToSenoneIDMap);$
- ⑦ $prior \leftarrow \text{EstimatePriorProbability}(featureSenoneIDPairs);$
- ⑧ $dnn \leftarrow \text{Backpropagate}(ptdnn, featureSenoneIDPairs);$
- ⑨ Return $dnnhmm = \{dnn, hmm, prior\}$

- The embedded Viterbi algorithm minimizes the average cross entropy for each speech utterance with T frames:

$$\mathcal{L}_{\text{CE}}(\theta) = - \sum_{t=1}^T \log p(q_t | \mathbf{x}_t; \theta)$$

DNN-HMM Hybrid ASR

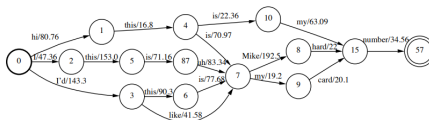
• Training DNN-HMM ASR systems (II):

- The cross-entropy criterion treats each frame independently
- Nevertheless, ASR is a sequence classification problem!
- Sequence-discriminative training techniques:
 - 1 Maximum mutual information (**MMI**)
 - 2 Boosted maximum mutual information (**BMMI**)
 - 3 Minimum phone error (**MPE**)
 - 4 State minimum Bayes risk (**sMBR**)

• Example: MMI

- MMI aims at maximizing the mutual information between the distributions of the observation and word sequences (*highly correlated to minimizing the expected sentence error*)

$$\mathcal{J}_{\text{MMI}}(\theta; \mathbb{S}) = \sum_{u=1}^{\mathcal{U}} \log P(\mathbf{W}^u | \mathbf{X}^u; \theta) = \sum_{u=1}^{\mathcal{U}} \log \frac{p(\mathbf{X}^u | \mathbf{s}^u; \theta)^\kappa P(\mathbf{W}^u)}{\sum_{\mathbf{W}} p(\mathbf{X}^u | \mathbf{s}^w; \theta)^\kappa P(\mathbf{W})}$$



[6] M. Mohri, https://cs.nyu.edu/~mohri/asr12/lecture_12.pdf

DNN-HMM Hybrid ASR

• Training DNN-HMM ASR systems (II):

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Training criterion	WER (%)
GMM-BMMI	18.6
DNN-CE	14.2
DNN-MMI	12.9
DNN-BMMI	12.9
DNN-MPE	12.9
DNN-sMBR	12.6

Word error rate (%) on the Switchboard dataset, [7] K. Vesely *et al.*, "Sequence-discriminative training of deep neural networks". In Proc. of Interspeech 2013

DNN-HMM Hybrid ASR: Key Issues

- Directly modeling context-dependent phone states (i.e., senones) is key (*overfitting alleviation*):

Model	Monophones	Senones
CD-GMM-HMM	—	23.6
CD-DNN-HMM (7x2k)	34.9	17.1

Word error rate (%) on the Switchboard dataset, [8] F. Seide *et al.*, "Conversational Speech Transcription Using Context-Dependent Deep Neural Networks". In Proc. of Interspeech 2011

- Deeper is better!

$L \times N$	WER (%)	$1 \times N$	WER (%)
1x2k	24.2	—	—
3x2k	18.4	—	—
5x2k	17.2	1x3,772	22.5
7x2k	17.1	1x4,634	22.6
—	—	1x16k	22.1

Word error rate (%) on the Switchboard dataset, [8]

- Use of temporal context:

Model	1 frame	11 frames
CD-DNN-HMM (7x2k)	23.2	17.1

Word error rate (%) on the Switchboard dataset, [8]

Robust ASR

- Gap in performance between humans and machines due to mismatch between the training and testing conditions of ASR systems:
 - ① **Speaker variabilities:** intra- (mood, illness...) and inter-speaker (vocal tract length, tone...) variability
 - ② **Environment variabilities:** background noise, reverberation...
- Speaker variability compensation:
 - ① Vocal tract length normalization (**VTLN**)
 - ② Feature-space maximum likelihood linear regression (**fMLLR**)

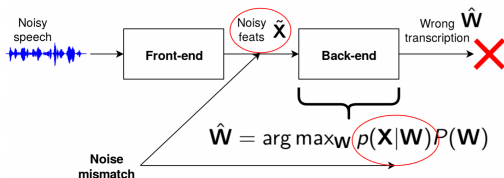
Model	No compensation	VTLN	fMLLR
CD-GMM-HMM	23.6	21.5	20.4
CD-MLP-HMM (1x2,048)	24.2	22.5	21.5
CD-DNN-HMM (7x2,048)	17.1	16.8	16.4

Word error rate (%) on the Switchboard dataset, [9] F. Seide *et al.*, "Feature engineering in context-dependent deep neural networks for conversational speech transcription". In Proc. of ASRU 2011

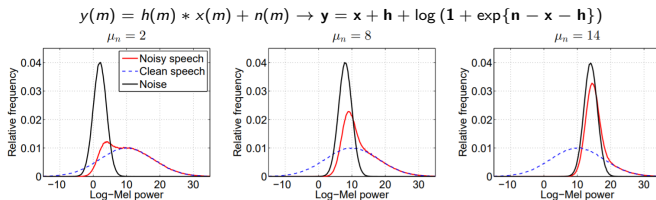
Robust ASR

- Environment variability compensation:

- Example: acoustic models are trained with clean speech data and we try to recognize noisy speech data → mismatch will cause a wrong transcription



- The statistical distribution of the speech energy is affected in the presence of background noise (when $\mathbf{h} = \mathbf{0}$):



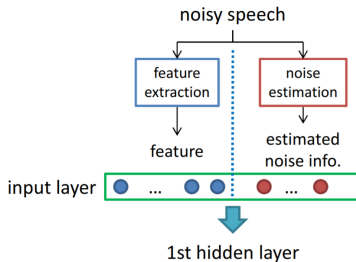
- Environment variability compensation:

- **THERE ARE PLENTY OF APPROACHES!**
- **Feature-space approaches:** noise-robust features (RASTA-PLP, TANDEM...), normalization of feature statistical moments (CMN, HEQ...) and speech/feature enhancement (Wiener filtering, DNN-based speech enhancement, beamforming...)
- **Model-based approaches:** model adaptation (CMLLR...) and adaptive training (fNAT, SAT...)
- **Compensation with explicit distortion modeling:** model adaptation or feature compensation (VTS...)
- **Missing data approaches:** ignoring unreliable elements during recognition (marginalization, SFD...) and data imputation (TGI...)
- ...

Robust ASR

- Environment variability compensation:

- **Multi-condition training:** training the acoustic model with distorted speech data from different acoustic conditions (*very effective if we can cover rather all the test acoustic conditions!*)
- **Noise-aware training (NAT):**



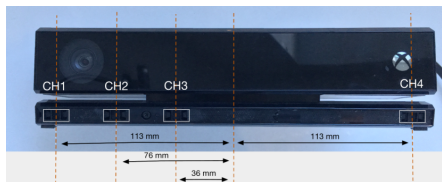
DNN-HMM System (7x2,048) WER (%)	
Multi-condition (MC) training	13.4
MC+Feature enhancement	13.8
MC+NAT	13.1
MC+Dropout	12.9
MC+NAT+Dropout	12.4

[10] A. Abe *et al.*, "Robust Speech Recognition using DNN-HMM Acoustic Model Combining Noise-aware Training with Spectral Subtraction". In Proc. of Interspeech 2015

Word error rate (%) on the Aurora-4 dataset, [11] M. Seltzer *et al.*, "An Investigation of Deep Neural Networks for Noise Robust Speech Recognition". In Proc. of ICASSP 2013

End-to-end ASR

- **End-to-end ASR:** a deep learning model is trained to directly map an input speech feature sequence to a sequence of characters/tokens
- End-to-end ASR systems are “simpler” / cleaner: there is no need for specific acoustic and language models with pronunciation lexicons
- **CHiME-6 Challenge:** distant microphone conversational speech recognition in everyday home environments
(<https://chimechallenge.github.io/chime6/overview.html>)



- In CHiME-6, DNN-HMM hybrid ASR systems still outperformed end-to-end ASR approaches (in 2020!)

End-to-end ASR: Basics

Recurrent neural networks (RNNs)

- Standard RNNs (general idea):

$$\mathbf{h}_t = \sigma(\mathbf{W}_{ih}\mathbf{x}_t + \mathbf{W}_{hh}\mathbf{h}_{t-1} + \mathbf{b}_h)$$

$$\mathbf{y}_t = \mathbf{W}_{ho}\mathbf{h}_t + \mathbf{b}_o$$

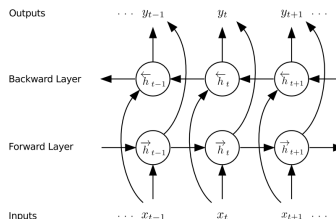
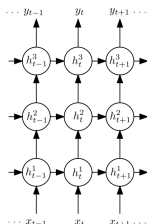
- Bidirectional RNNs:

$$\vec{\mathbf{h}}_t = \sigma(\mathbf{W}_{i\vec{h}}\mathbf{x}_t + \mathbf{W}_{\vec{h}\vec{h}}\vec{\mathbf{h}}_{t-1} + \mathbf{b}_{\vec{h}})$$

$$\overleftarrow{\mathbf{h}}_t = \sigma(\mathbf{W}_{i\overleftarrow{h}}\mathbf{x}_t + \mathbf{W}_{\overleftarrow{h}\overleftarrow{h}}\overleftarrow{\mathbf{h}}_{t+1} + \mathbf{b}_{\overleftarrow{h}})$$

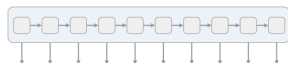
$$\mathbf{y}_t = \mathbf{W}_{\vec{h}o}\vec{\mathbf{h}}_t + \mathbf{W}_{\overleftarrow{h}o}\overleftarrow{\mathbf{h}}_t + \mathbf{b}_o$$

- Long short-term memory (LSTM), bidirectional LSTM (BiLSTM), gated recurrent units (GRUs)



[12] A. Graves and N. Jaitly, "Towards End-to-End Speech Recognition with Recurrent Neural Networks". In Proc. of ICML 2014

End-to-end ASR: CTC



h	h	h	h	h	h	h	h	h	h
e	e	e	e	e	e	e	e	e	e
l	l	l	l	l	l	l	l	l	l
o	o	o	o	o	o	o	o	o	o
ε	ε	ε	ε	ε	ε	ε	ε	ε	ε

h	e	ε	l	l	ε	l	l	o	o
h	h	e	l	l	ε	ε	l	ε	o
ε	e	ε	l	l	ε	ε	l	o	o

h	e	l	l	o
e	l	l	o	
h	e	l	o	

- Let $\mathbf{C} = (c_1, \dots, c_m)$ be the sequence of characters/tokens corresponding to $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_T)$
- We ignore an accurate alignment between \mathbf{C} and \mathbf{X} , and $m < T$
- **Connectionist temporal classification (CTC)** is an *alignment-free* algorithm
- CTC introduces the so-called blank token (ϵ)
- **CTC objective:** maximizing $P(\mathbf{C}|\mathbf{X}) = \sum_{\mathbf{A} \in \mathcal{A}_{\mathbf{X}, \mathbf{C}}} \prod_{t=1}^T P_t(\mathbf{c}|\mathbf{X})$ (e.g., $\mathbf{c} = \{h, e, l, o, \epsilon\}$)
- Decoding as usual, $\hat{\mathbf{C}} = \arg \max_{\mathbf{C}} P(\mathbf{C}|\mathbf{X})$

[13] A. Hannun, <https://distill.pub/2017/ctc/>

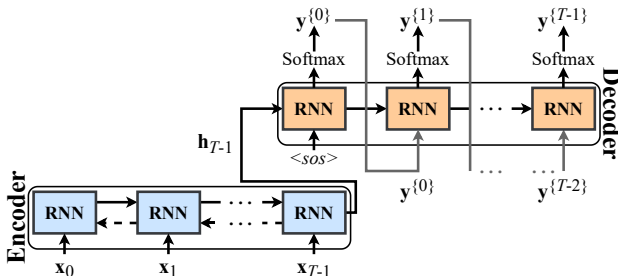
End-to-end ASR: Encoder-decoder Framework

Encoder-decoder framework

- The encoder is normally a BiLSTM, while the decoder, an LSTM:

$$\mathbf{h}_t = \text{Encoder}(\mathbf{x}_t, \mathbf{h}_{t-1})$$

$$\mathbf{s}_i = \text{Decoder}(\mathbf{s}_{i-1}, \mathbf{y}_{i-1})$$



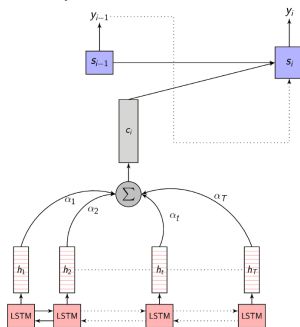
[14] I. López-Espejo *et al.*, "Deep Spoken Keyword Spotting: An Overview". IEEE Access, 2021

- Potential issue:** the encoder needs to condense all the required information (regardless the length of the input sequence) into a fixed-dimensional vector

End-to-end ASR: Attention

- We can **attend** to a context-relevant subset of $\{\mathbf{h}_1, \dots, \mathbf{h}_T\}$ instead of \mathbf{h}_T to “help” the decoder:

$$\mathbf{s}_i = \text{Decoder}(\mathbf{s}_{i-1}, \mathbf{y}_{i-1}, \mathbf{C}_i)$$

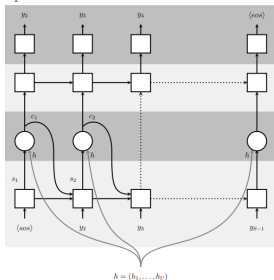


[15] S. Nadig, <https://medium.com/intel-student-ambassadors/attention-in-end-to-end-automatic-speech-recognition-9f9e42718d21>

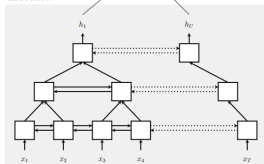
$$\mathbf{C}_i = \sum_{t=1}^T \alpha_{it} \mathbf{h}_t \quad \alpha_{it} = \text{softmax}(\text{AttentionFunction}(\mathbf{s}_{i-1}, \mathbf{h}_t))$$

End-to-end ASR: Attention Encoder-decoder

Speller



Listener

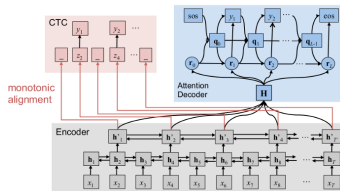


[16] W. Chan *et al.*, “Listen, Attend and Spell: A Neural Network for Large Vocabulary Conversational Speech Recognition”. In Proc. of ICASSP 2016

- **Problem with CTC: conditional label independence at decoding** → CTC needs an external language model to work well
- **Attention-based encoder-decoder ASR:** the alignment between **C** and **X** is learned using an attention mechanism

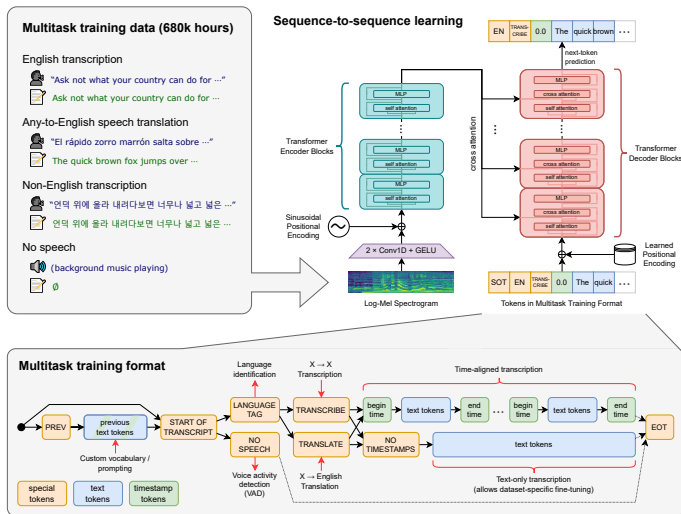
$$P(\mathbf{C}|\mathbf{X}) = \prod_{i=1}^m P(c_i|\mathbf{X}, c_1, \dots, c_{i-1})$$
- Attention-based encoder-decoder ASR is less robust to noise than CTC-based ASR → **CTC-attention ASR** has proven to be effective to improve recognition performance:

$$\text{Multitask learning: } \mathcal{L}_{\text{MTL}} = \lambda \mathcal{L}_{\text{CTC}} + (1 - \lambda) \mathcal{L}_{\text{Attention}}$$



CTC guides attention alignment to be monotonic

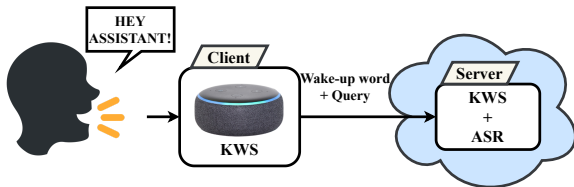
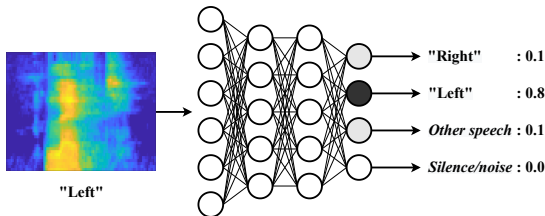
[15] S. Nadig, <https://medium.com/intel-student-ambassadors/attention-in-end-to-end-automatic-speech-recognition-9f9e42718d21>



[17] A. Radford *et al.*, “Robust Speech Recognition via Large-Scale Weak Supervision”. In Proc. of ICML 2023

Voice Control

Keyword Spotting Technology



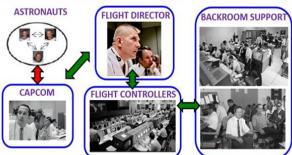
- Voice control is typically implemented through spoken **keyword spotting (KWS)**
- Spoken KWS can be defined as the task of identifying keywords in audio streams comprising speech

[14] I. López-Espejo et al., "Deep Spoken Keyword Spotting: An Overview". IEEE Access, 2021

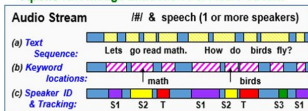
Applications and Ongoing Work

Topic Identification in NASA's Apollo Missions Audio

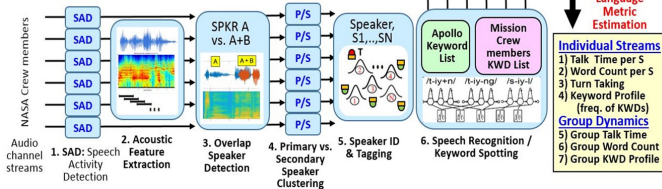
(i) Communication Overview for Apollo-MCC



(iii) CRSS-UTD DIARIZATION OUTPUT: Apollo Knowledge Extraction Per Audio Stream



(ii) Multi-Channel Diarization Speech Processing



[18] A. Joglekar *et al.*, "Fearless Steps APOLLO: Challenges in keyword spotting and topic detection for naturalistic audio streams". The Journal of the Acoustical Society of America, 2023

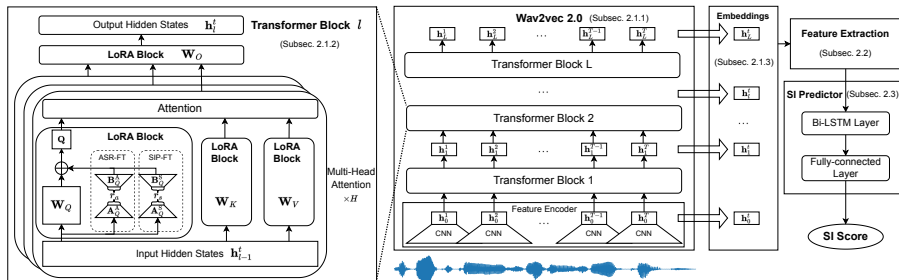
AGILE-KWS: A Giant Leap for Keyword Spotting

European Commission, Marie Curie Global Fellowships (HORIZON-MSCA-2021-PF-01)



Applications and Ongoing Work

No-Reference Speech Intelligibility Prediction



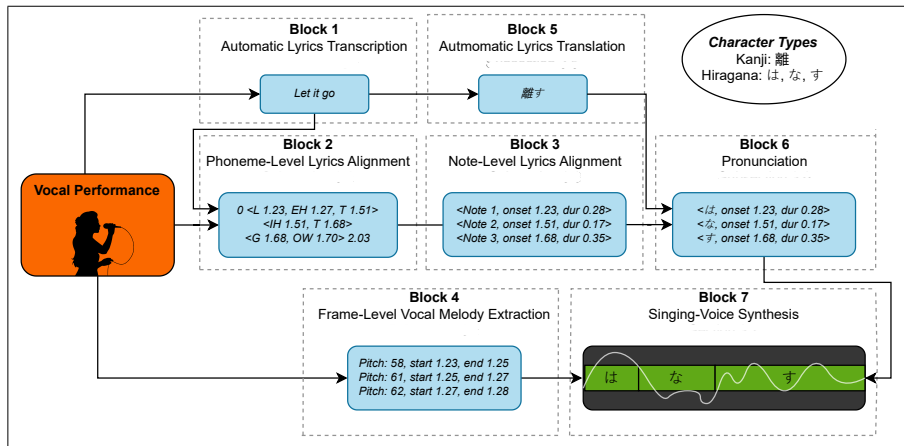
[19] H. Wang *et al.*, "No-Reference Speech Intelligibility Prediction Leveraging a Noisy-Speech ASR Pre-Trained Model". Submitted to Interspeech 2024

Self-supervised speech representation learning

- 1 Wav2vec 2.0 (🤖 https://huggingface.co/docs/transformers/model_doc/wav2vec2)
- 2 HuBERT (🤖 https://huggingface.co/docs/transformers/model_doc/hubert)
- 3 WavLM (🤖 https://huggingface.co/docs/transformers/model_doc/wavlm)

Applications and Ongoing Work

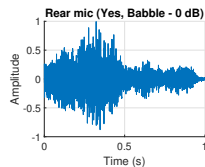
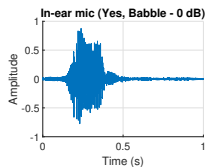
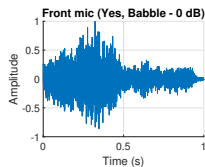
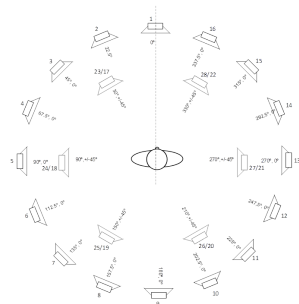
Singing-Voice to Singing-Voice Translation



[20] S. Antonisen and I. López-Espejo, "PolySinger: Singing-Voice to Singing-Voice Translation from English to Japanese". Submitted to ISMIR 2024

Applications and Ongoing Work

Noise-Robust Hearing Aid Voice Control



👤 **Wanna collaborate?** Reach out to iloes@ugr.es

AI in Speech Recognition and Voice Control

Iván López-Espejo

Open Day for Artificial Intelligence (ODAI'24)

Université Antonine

iloes@ugr.es

Thursday 18th April, 2024



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